## A170H PHOTOELECTRIC ANGLEENCODER

Precision photoelectric angle encoder A170H is used for precise angular displacement measurement of rotary tables, dividers, comparators, antennas and other high precision equipment.

It provides information about the value and direction of the motion. The encoder is used in automatic control, on-line gauging, process monitoring systems, etc.
The encoder has a rigid stainless steel construction and shaft collar coupling. Encoder is coupled via shaft collar. Three versions of output signals are available:

- A170H-A - sinusoidal signals, with amplitude approx. $11 \mu \mathrm{App} ;$


## MECHANICAL DATA

| Line number | 18000, 36000 |
| :---: | :---: |
| Number of output pulses per revolution for A170H-F | ```18000; 36000; 72000; 90000; 180000; 360000; 720000; 450000; 900000; 1800000; 3600000``` |
| Reference signal: | one per shaft revolution 36 per shaft revolution 72 per shaft revolution |
| Permissible mech. speed | $\leq 1000 \mathrm{rpm}$ |
| Max. operating speed (depends on number of output pulses) | 300 to 500 rpm |
| Permissible shaft load: <br> - axial <br> - radial | $\begin{aligned} & \text { 0,02 mm } \\ & 0,02 \mathrm{~mm} \end{aligned}$ |

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- A170H-AV - sinusoidal signals, with amplitude approx. 1 Vpp;
- A170H-F - square-wave signals (TTL) with integrated subdividing electronics for interpolation $\times 1, x 2$, $x 5, x 10, x 20, x 25, x 50$ and $\times 100$.

The modification with distance-coded reference marks is available.

| Accuracy | $\pm 2.0 ; \pm 2.5 ; \pm 5.0$ arc. sec |
| :--- | :--- |
| Starting torque at $20^{\circ} \mathrm{C}$ | $\leq 0.5 \mathrm{Nm}$ |
| Rotor moment of inertia | $<0.9 \times 10^{-3} \mathrm{kgm}$ |
| Protection (IEC 529) | PP 64 |
| Maximum weight without cable | 4.1 kg |
| Operating temperature | $0 \ldots+70^{\circ} \mathrm{C}$ |
| Storage temperature | $-30 \ldots+85^{\circ} \mathrm{C}$ |
| Maximum humidity (non condensing) | $98 \%$ |
| Permissible vibration | $\leq 100 \mathrm{~m} / \mathrm{s}^{2}$ |
| Permissible shock (6 ms) | $\leq 300 \mathrm{~m} / \mathrm{s}^{2}$ |



## ELECTRICAL DATA

| VERSION | A170H-A $\sim 11 \mu \mathrm{App}$ | A170H-AV $\sim 1 \mathrm{Vpp}$ | A170H-F $\downarrow$ TTL |
| :---: | :---: | :---: | :---: |
| Supply voltage ( $U_{p}$ ) | $+5 \vee \pm 5 \%$ | $+5 \mathrm{~V} \pm 5 \%$ | $+5 \vee \pm 5 \% ;$ |
| Max. supply current (without load) | 100 mA | 120 mA | 150 mA |
| Light source | LED | LED | LED |
| Incremental signals | Two sinusoidal $\mathrm{I}_{1}$ and $\mathrm{I}_{2}$ Amplitude at $1 \mathrm{k} \Omega$ load: $-11=7 \ldots 16 \mu A$ $-12=7 \ldots 16 \mu \mathrm{~A}$ | Differential sine $+\mathrm{A}-\mathrm{A}$ and $+\mathrm{B} /-\mathrm{B}$ Amplitude at $120 \Omega$ load: $\begin{aligned} & -A=0.6 \ldots 1.2 \mathrm{~V} \\ & -B=0.6 \ldots 1.2 \mathrm{~V} \end{aligned}$ | Differential square-wave U1/U1 and U2/V2. <br> Signal levels at 20 mA load current: <br> - low (logic " 0 ") $\leq 0.5 \mathrm{~V}$ <br> - high (logic "1") $\geq 2.4 \mathrm{~V}$ |
| Reference signal | One quasi-triangular I peak per revolution. Signal magnitude at $1 \mathrm{k} \Omega$ load: $-I_{0}=2 \ldots 8 \mu \mathrm{~A}$ (usable component) | One quasi-triangular +R and its complementary -R per revolution. Signals magnitude at $120 \Omega$ load - $\mathrm{R}=0.2 \ldots . .0 .8 \mathrm{~V}$ (usable component) | One differential square-wave UO/UO per revolution. Signal levels at 20 mA load current: <br> - low (logic "0") < 0.5 V <br> - high (logic "1") > 2.4 V |
| Maximum operating frequency | $(-3 \mathrm{~dB}$ cutoff $) \geq 160 \mathrm{kHz}$ | $(-3 \mathrm{~dB}$ cutoff $) \geq 180 \mathrm{kHz}$ | $160-2500 \mathrm{kHz}$ (depends on interpolation factor) |
| Direction of signals | I lags I, for clockwise rotation (viewed from encoder mounting side) | +B lags +A for clockwise rotation (viewed from encoder mounting side) | U2 lags U1 with clockwise rotation (viewed from encoder mounting side) |
| Maximum rise and fall time | - | - | $<0.5 \mu \mathrm{~s}$ |
| Standard cable length | 1 m , without connector | 1 m , without connector | 1 m , without connector |
| Maximum cable length | 5 m | 25 m | 25 m |
| Output signals | ( |  |  |

Note:

1. Maximum working rotation speed (with proper encoder counting) is limited by maximum operating frequency and maximum mechanical rotation speed.
2. If cable extension is used, power supply conductor cross-section should not be smaller than $0.5 \mathrm{~mm}^{2}$.

## MOUNTING REQUIREMENTS



ACCESSORIES

| CONNECTORS FOR CABLE | B12 12-pin round connector | C9 12-pin round connector | C12 <br> 12-pin round connector | D9 <br> 9-pin flat connector | D15 15-pin flat connector | RS10 10-pin round connector | ONC <br> 10-pin round connector |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DIGITAL READOUT DEVICES | CS3000 |  |  | CS5500 |  |  |  |
| EXTERNAL INTERPOLATOR | NK |  |  |  |  |  |  |

ORDER FORM


